



KR 10 R1100-2



Technical data

Maximum reach	1101 mm
Maximum payload	11.1 kg
Pose repeatability (ISO 9283)	± 0.02 mm
Number of axes	6
Mounting position	Floor; Ceiling; Wall;
	Desired angle
Footprint	208 mm x 208 mm
Weight	approx. 55 kg

Axis data

Motion range	
A1	±170 °
A2	-190 ° / 45 °
A3	-120 ° / 156 °
A4	±185 °
A5	±120 °
A6	±350 °

Operating conditions

Ambient temperature during operation	0 °C to 45 °C (273 K to 318 K)
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Protection rating

Protection rating (IEC 60529)	IP65 / IP67
Protection rating, robot wrist (IEC 60529)	IP65 / IP67

Controller

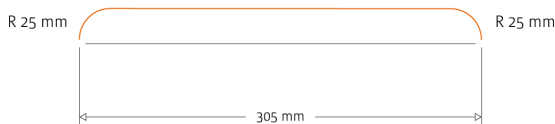
Controller	KR C5 micro; KR C4 compact
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Certificates

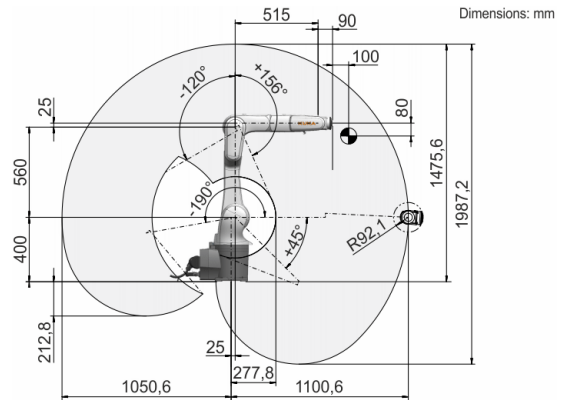
ESD requirements	IEC61340-5-1; ANSI/ESD S20.20
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Cycle time

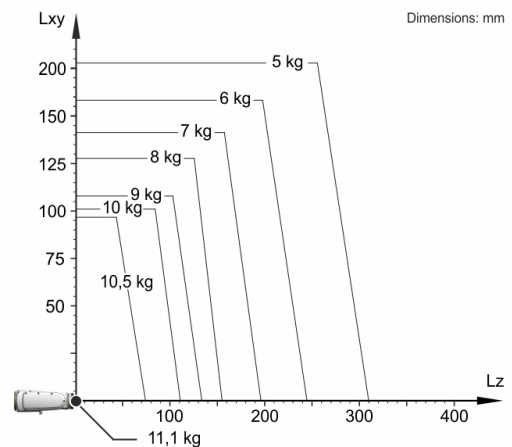
140 cycles per minute (25 mm / 305 mm / 25 mm, 1 kg)



Workspace graphic



Payload diagram



The KR 10 R1100-2 is designed for a rated payload of 5 kg in order to optimize the dynamic performance of the robot. The maximum payload of 11.1 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

Mounting flange

