



# KR 10 R900 WP



#### Technical data

Maximum reach	901.5 mm
Maximum payload	10 kg
Pose repeatability (ISO 9283)	± 0.03 mm
Number of axes	6
Mounting position	Floor;
	Ceiling;
	Wall;
	Desired angle
Footprint	320 mm x 320 mm
Weight	approx. 53 kg

#### Axis data

Motion range	
A1	±170 °
A2 A3 A4 A5 A6	-190 ° / 45 °
A3	-120 ° / 156 °
A4	±185 °
A5	±120 °
A6	±350 °

#### Operating conditions

Ambient temperature during opera-	5 °C to 45 °C (278 K to 318 K)
tion	

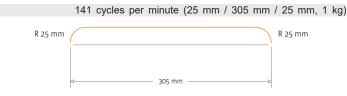
## **Protection rating**

Protection rating (IEC 60529)	IP67
Protection rating, robot wrist (IEC	IP67
60529)	

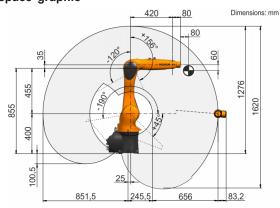
#### Controller

Controller	KR C5 micro;
	KR C4 compact

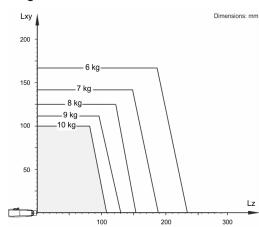
### Cycle time



## Workspace graphic



# Payload diagram



The KR 10 R900 WP is designed for a rated payload of 5 kg in order to optimize the dynamic performance of the robot. The maximum payload of 10 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

# Mounting flange

