## KR 6 R900 HM-SC



## Technical data

| Maximum reach | 901.5 mm |
| :---: | :---: |
| Maximum payload | 6 kg |
| Pose repeatability (ISO 9283) | $\pm 0.03 \mathrm{~mm}$ |
| Number of axes | 6 |
| Mounting position | Floor; <br> Ceiling; <br> Wall; <br> Desired angle |
| Footprint | $320 \mathrm{~mm} \times 320 \mathrm{~mm}$ |
| Weight | approx. 62 kg |
| Axis data |  |
| Motion range |  |
| A1 | $\pm 166{ }^{\circ}$ |
| A2 | $-188^{\circ} / 45^{\circ}$ |
| A3 | $-115^{\circ} / 144{ }^{\circ}$ |
| A4 | $\pm 185^{\circ}$ |
| A5 | $\pm 110^{\circ}$ |
| A6 | $\pm 350^{\circ}$ |

## Operating conditions

Ambient temperature during opera- $\quad 0{ }^{\circ} \mathrm{C}$ to $35{ }^{\circ} \mathrm{C}(273 \mathrm{~K}$ to 308 K$)$ tion

## Protection rating

| Protection rating (IEC 60529) | IP65 / IP67 |
| :--- | ---: |
| Protection rating, robot wrist (IEC | IP65 / IP67 |
| $60529)$  |  |

## Controller

| Controller | KR C5 micro; |
| :--- | ---: |
| KR C4 compact |  |

## Cycle time

144 cycles per minute ( $25 \mathrm{~mm} / 305 \mathrm{~mm} / 25 \mathrm{~mm}, 1 \mathrm{~kg}$ )


Workspace graphic


## Payload diagram



The KR 6 R900 HM-SC is designed for a rated payload of 3 kg in order to optimize the dynamic performance of the robot. The maximum payload of 6 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

## Mounting flange



