

# KR 10 R900 HM-SC



## **Technical data**

Maximum reach	901.5 mm
Maximum payload	10 kg
Pose repeatability (ISO 9283)	± 0.03 mm
Number of axes	6
Mounting position	Floor;
	Ceiling;
	Wall;
	Desired angle
Footprint	320 mm x 320 mm
Weight	approx. 62 kg

# Axis data

Motion range	
A1	±166 °
A2	-188 ° / 45 °
A2 A3 A4 A5 A6	-115 ° / 144 °
A4	±185 °
A5	±110 °
A6	±350 °

#### **Operating conditions**

Ambient temperature during opera-	0 °C to 35 °C (273 K to 308 K)
tion	

## **Protection rating**

Protection rating (IEC 60529)	IP65 / IP67
Protection rating, robot wrist (IEC	IP65 / IP67
60529)	

#### Controller

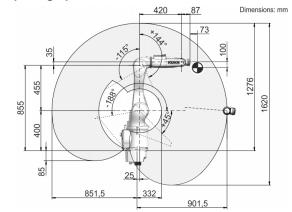
Controller	KR C5 micro;
	KR C4 compact

#### Cycle time

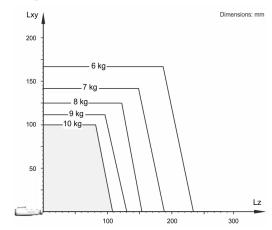
132 cycles per minute (25 mm / 305 mm / 25 mm, 1 kg)



## Workspace graphic

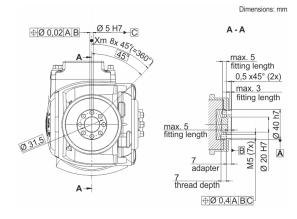


# Payload diagram



The KR 10 R900 HM-SC is designed for a rated payload of 5 kg in order to optimize the dynamic performance of the robot. The maximum payload of 10 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

#### Mounting flange



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