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KR 420 R3080 F



Technical data

Maximum reach	3076 mm
Rated payload	420 kg
Maximum payload	526 kg
Maximum supplementary load, rotat-	-
ing column / link arm / arm	
Pose repeatability (ISO 9283)	± 0.08 mm
Number of axes	6
Mounting position	Floor
Footprint	1050 mm x 1050 mm
Weight	approx. 2415 kg

Axis data

Motion range	
A1	±185 °
A2	-130 ° / 20 °
A3	-100 ° / 144 °
A4	±350 °
A5	±120 °
A6	±350 °
Speed with rated payload	
A1	90 °/s
A2	80 °/s
A3	75 °/s
A4	90 °/s
A5	83 °/s
A6	130 °/s

Operating conditions

Ambient temperature during opera- 10 $^\circ\mathrm{C}$ to 55 $^\circ\mathrm{C}$ (283 K to 328 K) tion

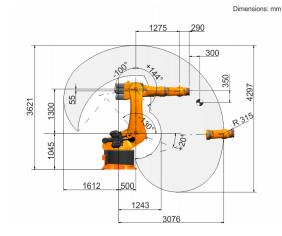
Protection rating

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Protection rating (IEC 60529)	IP65
Protection rating, robot wrist (IEC 60529)	IP67

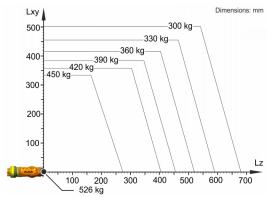
Controller

Controller	KR C5;
	KR C4

Workspace graphic

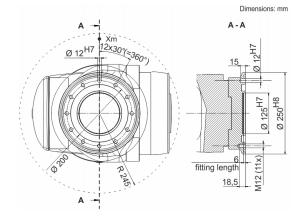


Payload diagram



The KR 420 R3080 F is designed for a rated payload of 420 kg in order to optimize the dynamic performance of the robot. The maximum payload of 526 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

Mounting flange



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