



KR 280 R3080



Technical data

| Maximum reach | 3076 mm |
|------------------------------------|-------------------|
| Rated payload | 280 kg |
| Maximum payload | 356 kg |
| Maximum supplementary load, rotat- | - |
| ing column / link arm / arm | |
| Pose repeatability (ISO 9283) | ± 0.08 mm |
| Number of axes | 6 |
| Mounting position | Floor |
| Footprint | 1050 mm x 1050 mm |
| Weight | approx. 2415 kg |

Axis data

| ±185 ° |
|----------------|
| -130 ° / 20 ° |
| -100 ° / 144 ° |
| ±350 ° |
| ±120 ° |
| ±350 ° |
| |
| 100 °/s |
| 90 °/s |
| 90 °/s |
| 120 °/s |
| 110 °/s |
| 160 °/s |
| |

Operating conditions

| Ambient temperature during opera- | 10 °C to 55 °C (283 K to 328 K) |
|-----------------------------------|---------------------------------|
| tion | |

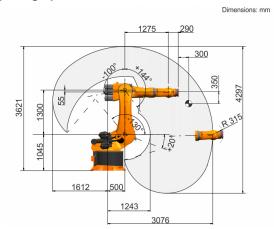
Protection rating

| • | |
|-------------------------------------|------|
| Protection rating (IEC 60529) | IP65 |
| Protection rating, robot wrist (IEC | IP65 |
| 60529) | |

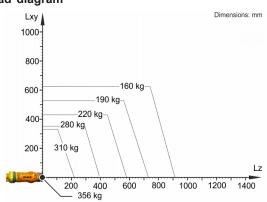
Controller

| Controller | KR C5; |
|------------|--------|
| | KR C4 |

Workspace graphic



Payload diagram



The KR 280 R3080 is designed for a rated payload of 280 kg in order to optimize the dynamic performance of the robot. The maximum payload of 356 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

Mounting flange

